

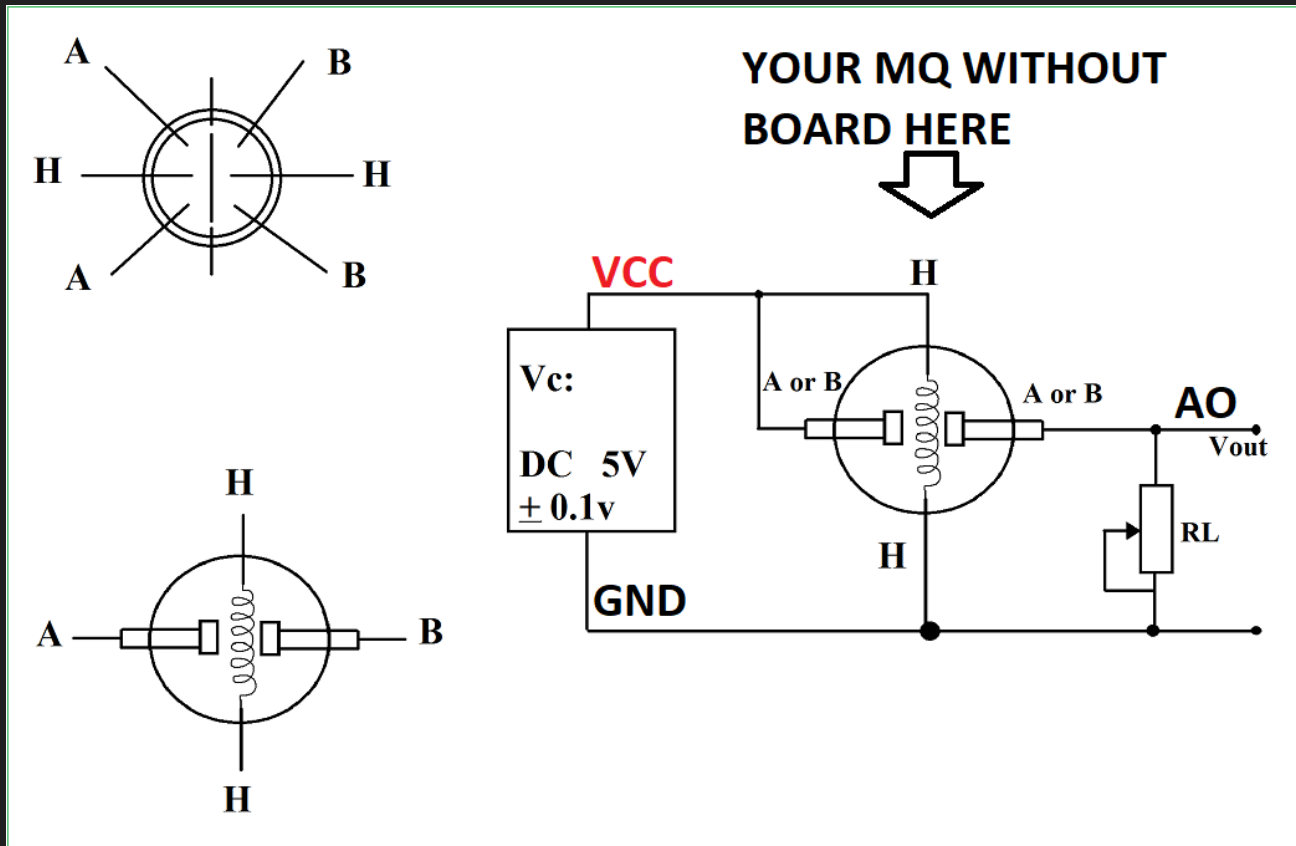
# MQSensorLib v2.0

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# New Features

- Implemented support for A2D external converters and ESP8266.
- (Example) Support to digital input, alarm status.
- Added calibration algorithm on the setup of all examples.
- Divided the calculation method on two methods (Linear – Exponential).
- Fixed words on spanish, translated to english (Inicializar -> Init)

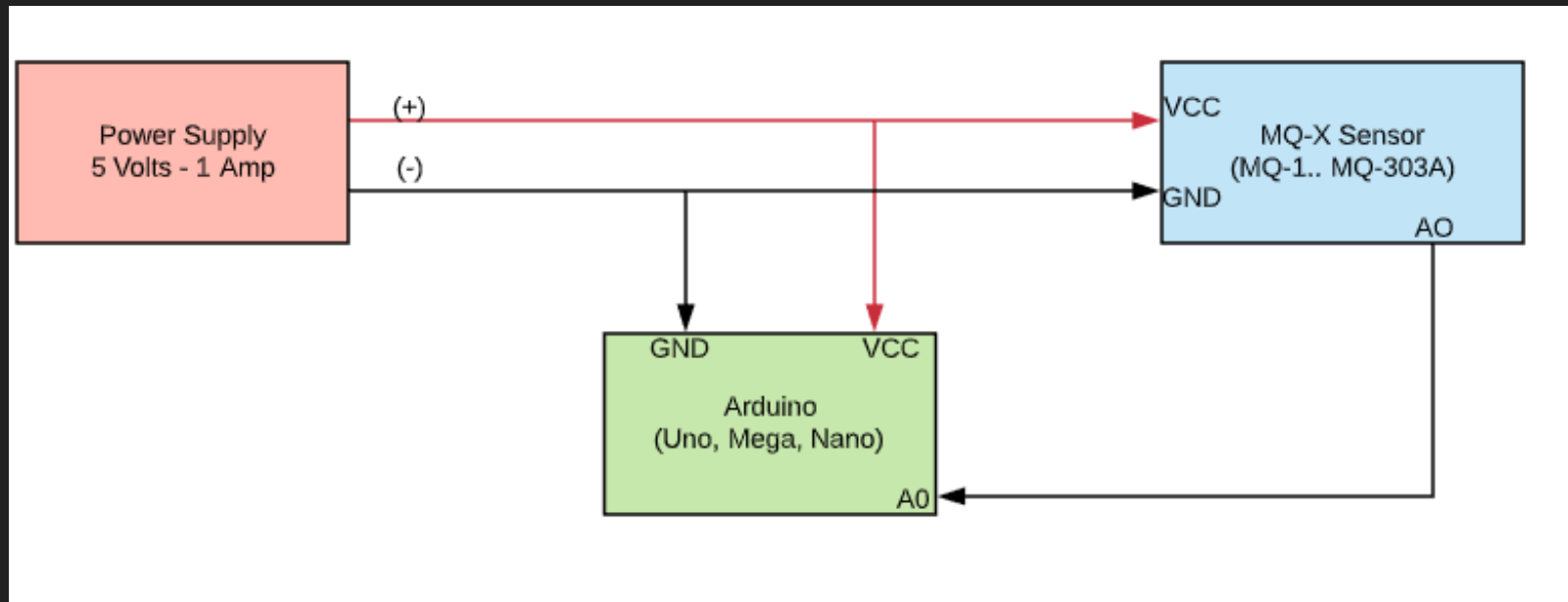
# MQSensor Connection (Global)



If you have an MQ into a board:  
1. Identify what's the value of your RL.  
2. Connect to your Arduino following next steps.

Or if you only have a sensor:  
1. Build your circuit.  
2. Identify your VCC, GND, AO.  
3. Connect to your Arduino following next steps.

# MQSensor and Arduino board (Wiring)



# MQSensor and Arduino board (Program)

```
#include <MQUnifiedsensor.h>
#define Board ("Arduino UNO")
#define Pin (A3) //Analog input 3 of your arduino
#define Type ("MQ-3") //MQ3
#define Voltage_Resolution (5)
#define ADC_Bit_Resolution (10) // For arduino UNO/MEGA/NANO
#define RatioMQ3CleanAir (60) //RS / R0 = 60 ppm
MQUnifiedsensor MQ3(Board, Voltage_Resolution, ADC_Bit_Resolution, Pin, Type);
void setup() {
    Serial.begin(9600);
    MQ3.init();
    MQ3.setRegressionMethod(1); //_PPM = a*ratio^b
    MQ3.setA(4.8387); MQ3.setB(-2.68); //Benzene
```

# MQSensor and Arduino board (Program)

```
float calcR0 = 0;
for(int i = 1; i<=10; i++)
{
  MQ3.update();
  calcR0 += MQ3.calibrate(RatioMQ3CleanAir);
  Serial.print(".");
}
MQ3.setR0(calcR0/10);
Serial.println(" done!");
}
```

# MQSensor and Arduino board (Program)

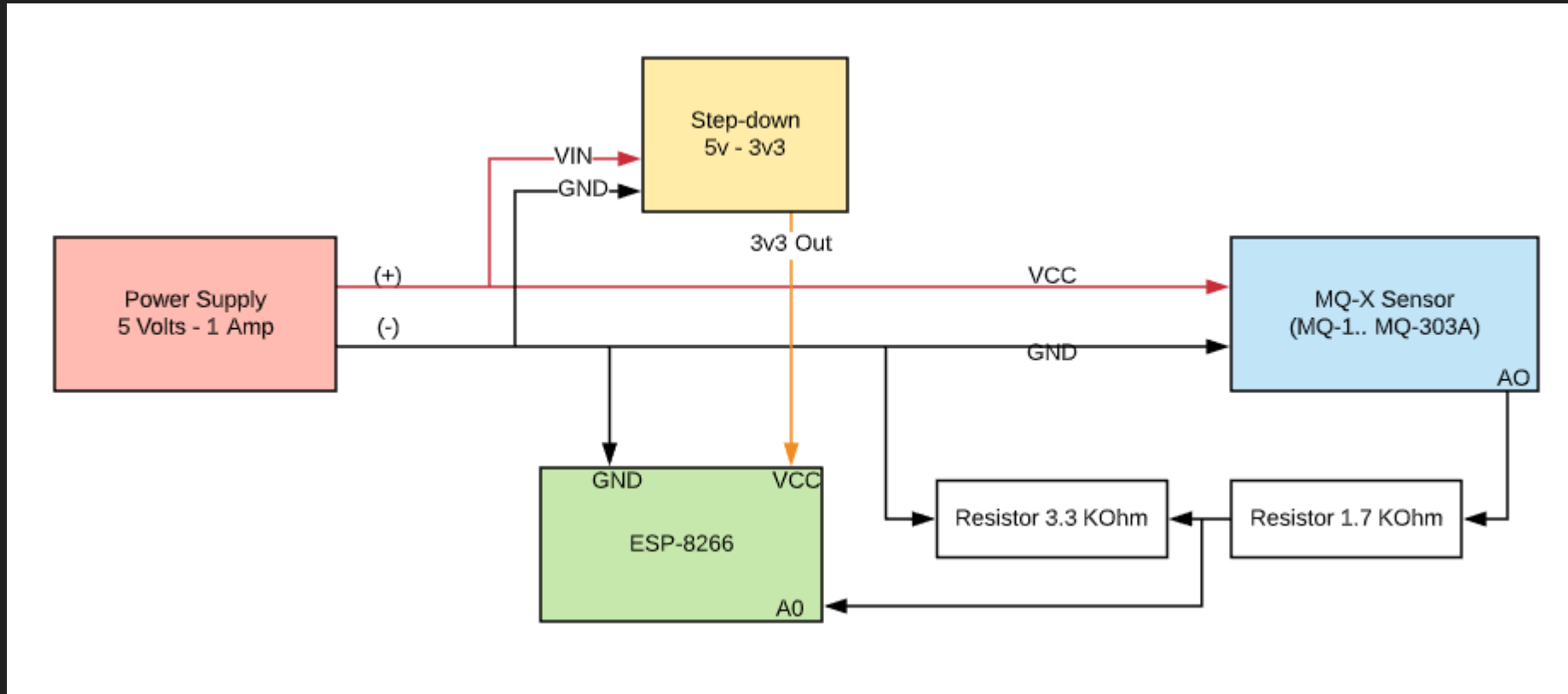
```
void loop() {  
  MQ3.update(); // Update data, the arduino will be read the voltage on the analog pin  
  MQ3.readSensor(); // Sensor will read PPM concentration using the model and a and b  
  values setted before or in the setup  
  MQ3.serialDebug(); // Will print the table on the serial port  
  delay(500); //Sampling frequency  
}
```

# MQSensor and Arduino board (Working)

```
COM3
19:31:53.360 -> Calibrating please wait..... done!.
19:31:53.809 ->
19:31:53.809 -> *****
19:31:53.914 -> MQ sensor reading library for arduino
19:31:53.983 -> Note: remember that all the parameters below can be modified during the program execution with the methods:
19:31:54.087 -> setR0, setRL, setA, setB where you will have to send as parameter the new value, example: mySensor.setR0(20); //R0 = 20KΩ
19:31:54.227 -> Authors: Miguel A. Califa U - Yersson R. Carrillo A - Ghiordy F. Contreras C
19:31:54.297 -> Contributors: Andres A. Martinez - Juan A. Rodriguez - Mario A. Rodriguez O
19:31:54.401 -> Sensor: MQ-3
19:31:54.401 -> Supply voltage: 5 VDC
19:31:54.435 -> ADC Resolution: 10 Bits
19:31:54.469 -> R0: 2.06 KΩ
19:31:54.469 -> RL: 10 KΩ
19:31:54.503 -> Model: Linear
19:31:54.503 -> MQ-3 -> a: 4.84 | b: -2.68
19:31:54.538 -> Development board: Arduino UNO
19:31:54.573 -> | *****MQ-3*****|
19:31:54.747 -> |ADC_In | Equation_V_ADC | Voltage_ADC | Equation_RS | Resistance_RS | EQ_Ratio | Ratio (RS/R0) | Equation_PPM | PPM |
19:31:55.373 -> |73.00| v = ADC*5/1024.00 | 0.36 | RS = ((5*RL)/Voltage) - RL| 130.14 | Ratio = RS/R0| 63.28 | ratio*a + b | 0.00 |
19:31:55.996 -> |70.00| v = ADC*5/1024.00 | 0.34 | RS = ((5*RL)/Voltage) - RL| 136.14 | Ratio = RS/R0| 66.20 | ratio*a + b | 0.00 |
19:31:56.655 -> |80.00| v = ADC*5/1024.00 | 0.39 | RS = ((5*RL)/Voltage) - RL| 117.87 | Ratio = RS/R0| 57.32 | ratio*a + b | 0.00 |
19:31:57.267 -> |80.00| v = ADC*5/1024.00 | 0.39 | RS = ((5*RL)/Voltage) - RL| 118.68 | Ratio = RS/R0| 57.71 | ratio*a + b | 0.00 |
19:31:57.921 -> |79.00| v = ADC*5/1024.00 | 0.39 | RS = ((5*RL)/Voltage) - RL| 119.49 | Ratio = RS/R0| 58.11 | ratio*a + b | 0.00 |
19:31:58.546 -> |80.00| v = ADC*5/1024.00 | 0.39 | RS = ((5*RL)/Voltage) - RL| 117.87 | Ratio = RS/R0| 57.32 | ratio*a + b | 0.00 |
19:31:59.204 -> |78.00| v = ADC*5/1024.00 | 0.38 | RS = ((5*RL)/Voltage) - RL| 121.15 | Ratio = RS/R0| 58.91 | ratio*a + b | 0.00 |
19:31:59.828 -> |75.00| v = ADC*5/1024.00 | 0.37 | RS = ((5*RL)/Voltage) - RL| 126.40 | Ratio = RS/R0| 61.46 | ratio*a + b | 0.00 |
19:32:00.451 -> |77.00| v = ADC*5/1024.00 | 0.37 | RS = ((5*RL)/Voltage) - RL| 125.50 | Ratio = RS/R0| 61.03 | ratio*a + b | 0.00 |
19:32:01.105 -> |77.00| v = ADC*5/1024.00 | 0.37 | RS = ((5*RL)/Voltage) - RL| 123.73 | Ratio = RS/R0| 60.16 | ratio*a + b | 0.00 |
19:32:01.733 -> |77.00| v = ADC*5/1024.00 | 0.38 | RS = ((5*RL)/Voltage) - RL| 122.86 | Ratio = RS/R0| 59.74 | ratio*a + b | 0.00 |
```



# MQSensor and ESP8266 (Wiring)



# MQSensor and ESP8266 (Program)

```
//Include the library
#include <MQUnifiedsensor.h>
#define Board ("Arduino UNO")
#define Pin (A3) //Analog input 3 of your Arduino
#define Type ("MQ-3") //MQ3
#define Voltage_Resolution (3.3)
#define ADC_Bit_Resolution (10) // For arduino UNO/MEGA/NANO
MQUnifiedsensor MQ3(Board, Voltage_Resolution, ADC_Bit_Resolution, Pin, Type);
void setup() {
    Serial.begin(9600); //Init serial port
    MQ3.setRegressionMethod(1); //_PPM = a*ratio^b
    MQ3.setA(4.8387); MQ3.setB(-2.68); //Benzene
    MQ3.init();
}
```

# MQSensor and ESP8266 (Program)

```
Serial.print("Calibrating please wait.");
float calcR0 = 0;
for(int i = 1; i<=10; i++)
{
  MQ3.update(); // Update data, the arduino will be read the voltage on the analog pin
  calcR0 += MQ3.calibrate(RatioMQ3CleanAir);
  Serial.print(".");
}
MQ3.setR0(calcR0/10);
Serial.println(" done!");
}
```

# MQSensor and ESP8266 (Program)

```
void loop() {  
  MQ3.update(); // Update data, the arduino will be read the voltage on the analog pin  
  MQ3.readSensor();  
  MQ3.serialDebug(); // Will print the table on the serial port  
  delay(500); //Sampling frequency  
}
```

# MQSensor and ESP8266 (Result)

```

COM3
19:55:30.487 -> $E$|v@MMDS4C(RSSCalibrating please wait..... done!.
19:55:30.935 ->
19:55:30.935 -> *****
19:55:31.072 -> MQ sensor reading library for arduino
19:55:31.142 -> Note: remember that all the parameters below can be modified during the program execution with the methods:
19:55:31.245 -> setR0, setRL, setA, setB where you will have to send as parameter the new value, example: mySensor.setR0(20); //R0 = 20KΩ
19:55:31.384 -> Authors: Miguel A. Califa U - Yersson R. Carrillo A - Ghiordy F. Contreras C
19:55:31.453 -> Contributors: Andres A. Martinez - Juan A. Rodriguez - Mario A. Rodriguez O
19:55:31.557 -> Sensor: MQ-3
19:55:31.557 -> Supply voltage: 3 VDC
19:55:31.592 -> ADC Resolution: 10 Bits
19:55:31.626 -> R0: 41.02 KΩ
19:55:31.626 -> RL: 10 KΩ
19:55:31.661 -> Model: Exponential
19:55:31.661 -> MQ-3 -> a: 4.84 | b: -2.68
19:55:31.696 -> Development board: Arduino UNO
19:55:31.731 -> | *****MQ-3*****|
19:55:31.869 -> |ADC_In | Equation_V_ADC | Voltage_ADC | Equation_RS | Resistance_RS | EQ_Ratio | Ratio (RS/R0) | Equation_PPM | PPM |
19:55:32.454 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2912.86 | Ratio = RS/R0| 71.00 | ratio*a + b | 0.00 |
19:55:33.005 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2547.50 | Ratio = RS/R0| 62.10 | ratio*a + b | 0.00 |
19:55:33.561 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2912.86 | Ratio = RS/R0| 71.00 | ratio*a + b | 0.00 |
19:55:34.151 -> |5.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2263.33 | Ratio = RS/R0| 55.17 | ratio*a + b | 0.00 |
19:55:34.705 -> |5.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2263.33 | Ratio = RS/R0| 55.17 | ratio*a + b | 0.00 |
19:55:35.261 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2547.50 | Ratio = RS/R0| 62.10 | ratio*a + b | 0.00 |
19:55:35.817 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2263.33 | Ratio = RS/R0| 55.17 | ratio*a + b | 0.00 |
19:55:36.407 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2547.50 | Ratio = RS/R0| 62.10 | ratio*a + b | 0.00 |
19:55:36.963 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2547.50 | Ratio = RS/R0| 62.10 | ratio*a + b | 0.00 |
19:55:37.519 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2547.50 | Ratio = RS/R0| 62.10 | ratio*a + b | 0.00 |
19:55:38.074 -> |4.00| v = ADC*3/1024.00 | 0.01 | RS = ((3*RL)/Voltage) - RL| 2547.50 | Ratio = RS/R0| 62.10 | ratio*a + b | 0.00 |

```

Autoscroll  Show timestamp

# MQSensor A2D External

Method **setADC(Your-ADC-VALUE)** replace **update()**

- \*\* Wiring is custom and it depends what A2D that you use.
- \*\* You need to set first the ADC Bit resolution and make sure is correct.
- \*\* After your read ADC method you Will set the value for MQ library using `MQ.setADC(yourADCReadedValue)`.
- \*\* Use the library looks like sensor connected direct to your analog pin of board.
- \*\* Please remember, A0 pin doesnt matter, you can set 0...100, any.

# MQSensor Digital Input

- \*\* Digital input is only alert output.
- \*\* Its setted before pre-heat and its experimental.
- \*\* Messages Will show on the serial output.

# Any Questions:

Options:

1. Open issue on our github repo.
2. Contact us email: [miguelangel5612@gmail.com](mailto:miguelangel5612@gmail.com)
3. Comment this video bellow section.